

APPLICATION NOTE

ST6x86 BIOS WRITER'S GUIDE

1.0 Introduction

1.1 Scope

This document is intended for ST6x86 system BIOS writers. It is not a stand alone document but supplements other SGS-THOMSON and ST6x86 documentation including: ST6x86 Data Book, ST6x86/PEN-TIUM(P54C) Bus Interface Differences, SGS-THOMSON SMM Programmer's Guide. This document includes recommendations for ST6x86 detection and ST6x86 configuration register settings. Configuration register settings described in this document apply to ST6x86 step A and higher.

The recommended settings are optimized for both performance and compatibility in a Windows95, Plug and Play (PnP), PCI-based system. Issues regarding optimum performance, CPU detection, chipset initialization, memory discovery, I/O recovery time, and others are described in detail.

1.2 ST6x86 Configuration Registers

The ST6x86 uses on-chip configuration registers to control the on-chip cache, system management mode (SMM), device identification, and other ST6x86 unique features. The on-chip registers are used to activate advanced features including performance enhancements. These performance features may be enabled "globally" in some cases, or by a user-defined address region. The flexible configuration of the ST6x86 is intended to fit a wide variety of systems.

The Importance of Non-Cacheable Regions

The ST6x86 has eight internal user-defined Address Region Registers. Among other attributes, the regions define cacheability vs. non-cacheability of the address regions. Using this cacheability information, the ST6x86 is able to implement high performance features, that would otherwise not be possible. A non-cacheable region implies that read sourcing from the write buffers, data forwarding, data bypassing, speculative reads, and fill buffer streaming are disabled for memory accesses within that region. Additionally, strong cycle ordering is also enforced. Although negating KEN# during a memory access on the bus prevents a cache line fill, it does not fully disable these performance features. In other words, negating KEN# is NOT equivalent to establishing a non-cacheable region in the ST6x86.

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2.0 Detecting a SGS-THOMSON ST6x86 CPU

ST6x86 detection must first be determined by the BIOS during Power-On Self Test using the method described in Section 2.1. Allowing ST6x86 detection using CPUID at runtime is covered in Section 2.4.

It is important to note that the ST6x86's CPUID instruction is disabled following reset. SGS-THOMSON's compatibility testing has found that some popular software does not correctly check the CPUID return values (e.g. Vendor Identification String and Family fields). This results in misidentification of CPU features which may cause a variety of runtime errors. By disabling the CPUID instruction, the ST6x86 CPU is assured to run code compatible with the 486 instruction set and programming model.

2.1 Detecting a SGS-THOMSON CPU

Since CPUID is disabled by default, it cannot be used to identify the ST6x86 during BIOS POST. The correct method for detecting the presence of an ST6x86 microprocessor during BIOS POST is a two step process. First, a SGS-THOMSON brand CPU must be detected. Second, the CPU's Device Identification Registers (DIRs) provide the CPU model and stepping information. Alternate methods of detecting the CPU are not recommended. These include detection algorithms using the value of EDX following reset, and other signature methods of determining if the CPU is an 8086, 80286, 80386, or 80486.

Detection of a SGS-THOMSON brand CPU is implemented by checking the state of the undefined flags following execution of the divide instruction which divides 5 by 2 (5/2). The undefined flags in a SGS-THOMSON microprocessor remain unchanged following the divide. Alternate CPUs modify some of the undefined flags. Using operands other than 5 and 2 may prevent the algorithm from working correctly. Appendix A contains example code for detecting a SGS-THOMSON CPU using this method.

2.2 Detecting CPU Type and Stepping using DIRs

Once a SGS-THOMSON brand CPU is detected, the model and stepping of the CPU can be determined. All SGS-THOMSON CPUs contain Device Identification Registers (DIRs) that exist as part of the configuration registers. The DIRs for all SGS-THOMSON CPUs exist at configuration register indexes 0FEh and 0FFh. (See Chapter 3 for additional information.) Table 2-1 specifies the contents of the ST6x86 DIRs.

DIR0 bits [7:3] = 00110h indicate an ST6x86 CPU is present, DIR0 bits [2:0] indicate the core-to-bus clock ratio, and DIR1 contains stepping information. Clock ratio information is provided to assist calculations in determining bus frequency once the CPU's core frequency has been calculated. Proper bus speed settings are critical to overall system performance.

Table 2.1 ST6x86 Device I	dentification Re	gister
---------------------------	------------------	--------

Register	Description	Bit Position	Contents	Core/Bus Clock Ratios
			30h or 32h	1/1
DIDO	CPU Model	7-0	31h or 33h	2/1
DIR0			35h or 37h	3/1
			34h or 36h	4/1
DIR1	Device Stepping	7-0	xxh	

x = TBD

2.3 Determining ST6x86 Operating Frequency

Determining the operating frequency of the CPU is normally required for correct initialization of the system logic. Typically, a software timing loop with known instruction clock counts is timed using legacy hardware (the 8254 timer/counter circuits) within the PC. Once the operating frequency of the ST6x86's core is known, DIR0 bits (2:0) can be examined to calculate the bus operating frequency.

Careful selection of instructions and operands must be used to replicate the exact clock counts detailed in the Instruction Set Summary in the ST6x86 Data Book. An example code sequence for determining the ST6x86's operating frequency is detailed in Appendix B and Appendix C. The core loop uses a

series of five IDIV instructions within a LOOP instruction. IDIV was chosen because it is an exclusive instruction meaning that it executes in the ST6x86 x pipeline with no other instruction in the y pipeline. This allows for more predictable execution times as compared to using non-exclusive instructions.

The ST6x86 instruction clock count for IDIV varies from 17 to 45 clocks for a doubleword divide depending on the value of the operands. The code example in the appendices uses "0" divided by "1" which takes only 17 clocks to complete. The LOOP instruction clock count is 1. Therefore, the overall clock count for the inner loop in this example is 86 clocks.

2.4 CPUID Instruction

The CPUID instruction is disabled following reset to improve compatibility with existing software. It can be enabled by setting the CPUIDEN bit in configuration register CCR4. It is recommend that all BIOS vendors include a CPUID enable/disable field in the CMOS setup to allow the end user to enable the CPUID instruction. CPUID must default to disabled and remain disabled unless enabled by the end user.

The CPUID instruction, opcode **0FA2h**, provides information indicating SGS-THOMSON as the vendor and the family, model, stepping, and CPU features. Additional documentation on the CPUID instruction and how alternate CPUs execute this instruction can be found in the Pentium Processor User's Manual, Volume 3, page 25-62; Pentium Processor User's Manual, Volume 1, Page 3-7; and Intel's application note AP-485.

The EAX register provides the input value for the CPUID instruction. The EAX register is loaded with a value to indicate what information should be returned by the instruction.

Following execution of the CPUID instruction with an input value of "0" in EAX, the EAX, EBX, ECX and EDX registers contain the information shown in Figure 2-1. EAX contains the highest input value understood by the CPUID instruction, which for the ST6x86 is "1". EBX, ECX and EDX contain the vendor identification string "CyrixInstead".

Following execution of the CPUID instruction with an input value of "1" loaded in EAX, EAX[15:0] will contain the value of 053x. EDX bit [0] contains a "1" indicating that an FPU is on chip.

```
switch (EAX)
 {
 case (0):
                              EAX := 1
                EBX := 69 72 79 43/* 'i' 'r' 'v' 'C' */
                EDX := 73 6e 49 78/* 's' 'n' 'I' 'x' */
                ECX := 64 61 65 74/* 'd' 'a' 'e' 't' */
                               break
 case (1):
                          EAX[7:0] := 3xh
                         EAX[15:8] := 05h
            EDX[0] := 1 /* 1=FPU Built In,0=No FPU */
                               break
  default:
                 EAX, EBX, ECX, EDX: Undefined
  }
```

Figure 2-1. Information Returned by the CPUID Instruction

2.5 EDX Value Following Reset

Some CPU detection algorithms may use the value of the CPU's EDX register following reset. The ST6x86's EDX register contains the data shown below following a reset initiated using the RESET pin:

EDX[31:16] = undefined

EDX[15:8] = 05h

EDX[7:0] = 3x

The value in EDX does not identify the vendor of the CPU. Therefore, EDX alone cannot be used to determine if a SGS-THOMSON CPU is present. However, BIOS should preserve the contents of EDX so that applications can use the EDX value when performing a user-defined shutdown (e.g. a reset performed with data 0Ah in the Shutdown Status byte (Index 0Fh) of the CMOS RAM Map).

3.0 ST6x86 Configuration Register Index Assignments

On-chip configuration registers are used to control the on-chip cache, system management mode and other ST6x86 unique features.

3.1 Accessing a Configuration Register

Access to the configuration registers is achieved by writing the index of the register to I/O port 22h. I/O port 23h is then used for data transfer. Each I/O port 23h data transfer must be preceded by an I/O port 22h register index selection, otherwise the second and later I/O port 23h operations are directed off-chip and produce external I/O cycles. Reads of I/O port 22h are always directed off-chip. Appendix D contains example code for accessing the ST6x86 configuration registers.

3.2 ST6x86 Configuration Register Index Assignments

Table 3-1 lists the ST6x86 configuration register index assignments. After reset, configuration registers with indexes CO-CFh and FC-FFh are accessible. In order to prevent potential conflicts with other devices which may use ports 22 and 23h to access their registers, the remaining registers (indexes 00-BFh, D0-FBh) are accessible only if the MAPEN(3-0) bits in CCR3 are set to 1h. With MAPEN(3-0) set to 1h any access to an index in the 00-FFh range does not create external I/O bus cycles. Registers with indexes C0-CFh, FC-FFh are accessible regardless of the state of the MAPEN bits. If the register index number is outside the C0-CFh or FC-FFh ranges, and MAPEN is set to 0h, external I/O bus cycles occur. Table 3-1 lists the MAPEN values required to access each ST6x86 configuration register. The configuration registers are described in more detail in the following sections.

The ST6x86 configuration registers can be grouped into four areas:

- Configuration Control Registers (CCRs)
- Address Region Registers (ARRs)
- Region Control Registers (RCRs)
- Device Identification Registers (DIRs)

CCR bits independently control ST6x86 features. ARRs and RCRs together define regions of memory with specific attributes. DIRs are used for CPU detection as discussed earlier in Chapter 2. All bits in the configuration registers are initialized to zero following reset unless specified otherwise. The appropriate configuration register bit settings vary depending on system design. Recommendations for optimal settings for a typical PC environment are discussed in Chapter 4.

Table 3.1 Configuration Register Index Assignment

Register Index	Register Name	Acronym	Width (BITS)	MAPEN(3-0)
00h-BFh	Reserved			
COh	Configuration Control 0	CCR0	8	х
C1h	Configuration Control 1	CCR1	8	x
C2h	Configuration Control 2	CCR2	8	х
C3h	Configuration Control 3	CCR3	8	x
C4h-C6h	Address Region 0	ARR0	24	Х
C7h-C9h	Address Region 1	ARR1	24	x
CAh-CCh	Address Region 2	ARR2	24	x
CDh-CFh	Address Region 3	ARR3	24	x
D0h-D2h	Address Region 4	ARR4	24	1 h
D3h-D5h	Address Region 5	ARR5	24	1 h
D6h-D8h	Address Region 6	ARR6	24	1 h
D9h-DBh	Address Region 7	ARR7	24	1 h
DCh	Region Configuration 0	RCR0	8	1 h
DDh	Region Configuration 1	RCR1	8	1 h
DEh	Region Configuration 2	RCR2	8	1 h
DFh	Region Configuration 3	RCR3	8	1 h
E0h	Region Configuration 4	RCR4	8	1 h
E1h	Region Configuration 5	RCR5	8	1 h
E2h	Region Configuration 6	RCR6	8	1 h
E3h	Region Configuration 7	RCR7	8	1 h
E4h-E7h	Reserved			
E8h	Configuration Control 4	CCR4	8	1 h
E9h	E9h Configuration Control 5		8	1 h
EAh-FDh	EAh-FDh Reserved			
FEh	Device Identification 0	DIR0	8	х
FFh	Device Identification 1	DIR1	8	x

X = Don' t Care

3.3 Configuration Control Registers (CCR0-5)

There are six CCRs in the ST6x86 which control the cache, power management and other unique features. The following paragraphs describe the CCRs and associated bit definitions in detail.

3.3.1 Configuration Control Register 0 (CCR0)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	NC1	Reserved

Table 3.2 CCR0 Bit Definitions

Bit Name	Bit No.	Description
NC1	1	If set, designates 640KBytes -1MByte address region as non-cacheable.

3.3.2 Configuration Control Register 1 (CCR1)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
SM3	Reserved	Reserved	NO_LOCK	Reserved	SMAC	USE_SMI	Reserved

Table 3.3 CCR1 Bit Definitions

Bit Name	Bit No.	Description
SM3	7	If set, designates Address Region Register 3 for SMM address space.
NO_LOCK	4	If set, all bus cycles are issued with the LOCK# pin negated except page table accesses and interrupt acknowledge cycles. Interrupt acknowledge cycles are executed as locked cycles even though LOCK# is negated. With NO_LOCK set, previously non-cacheable locked cycles are executed as unlocked cycles and therefore, may be cached. This results in higher CPU performance. See the section on Region Configuration Registers (RCR) for more information on eliminating locked CPU bus cycles only in specific address regions.
SMAC 2		If set, any access to addresses within the SMM address space access system management memory instead of main memory. SMI# input is ignored while SMAC is set. Setting SMAC=1 allows access to SMM memory without entering SMM. This is useful for initializing or testing SMM memory.
USE_SMI 1		If set, SMI# and SMIACT# pins are enabled. If clear, SMI# pin is ignored and SMIACT# pin is driven inactive.

3.3.3 Configuration Control Register 2 (CCR2)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
USE_SUSP	Reserved	Reserved	WPR1	SUSP_HLT	LOCK_NW	Reserved	Reserved

Table 3.4 CCR2 Bit Definition

Bit Name	Bit No.	Description
		If set, SUSP# and SUSPA# pins are enabled.
USE SUSP	7	If clear, SUSP# pin is ignored and SUSPA# pin floats.
7		These pins should only be enabled if the external system logic (chipset) support them.
WPR1	4	If set, designates that any cacheable accesses in the 640 KBytes-1MByte address region are write-protected. With WPR1=1, any attempted write to this range will not get issued to the external bus.
SUSP_HLT	3	If set, execution of the HLT instruction causes the CPU to enter low power suspend mode. This bit should be used cautiously since the CPU must recognize and service an INTR, NMI or SMI to exit the "HLT initiated" suspend mode.
LOCK_NW	2	If set, the NW bit in CR0 becomes read only and the CPU ignores any writes to this bit

3.3.4 Configuration Control Register 3 (CCR3)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
MAPEN3	MAPEN2	MAPEN1	MAPEN0	Reserved	LINBRST	NMI_EN	SMI_LOCK

Table 3.5 CCR3 Bit Definitions

Bit Name	Bit No.	Description				
		If set to 0001 binary (1h), all configuration registers are accessible.				
MAPEN(3-0)	7-4	If clear, only configuration registers with indexes C0-CFh, FEh and FFh are accessible.				
		If set, the ST6x86 will use a linear address sequence when performing burst cycles.				
LINBRST	2	If clear, the ST6x86 will use a "1+4" address sequence when performing burst cycles. The "1+4" address sequence is compatible with the Pentium's burst address sequence.				
NMI_EN	1	If set, NMI interrupt is recognized while in SMM. This bit should only be set while in SMM, after the appropriate NMI interrupt service routine has been setup.				
		If set, the CPU prevents modification of the following SMM configuration bits, except when operating in SMM:				
		CCR1 USE_SMI, SMAC, SM3				
SMI_LOCK	0	CCR3 NMI_EN				
		ARR3 Starting address and block size.				
		Once set, the SMI_LOCK bit can only be cleared by asserting the RESET pin.				

3.3.5 Configuration Control Register 4 (CCR4)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
CPUIDEN	Reserved	Reserved	DTE_EN	Reserved		IORT(2-0)	

Table 3.6 CCR4 Bit Definitions

Bit Name	Bit No.	Description
CPUIDEN	7	If set, bit 21 of the EFLAG register is write/readable and the CPUID instruction will execute normally. If clear, bit 21 of the EFLAG register is not write/readable and the CPUID instruction is an invalid opcode.
DTE_EN	4	If set, the Directory Table Entry cache is enabled.
IORT(2-0)	2-0	Specifies the minimum number of bus clocks between I/O accesses (I/O recovery time). The delay time is the minimum time from the end of one I/O cycle to the beginning of the next (i.e. BRDY# to ADS# time). Oh = 1 clock 1h = 2 clocks 2h = 4 clocks 3h = 8 clocks 4h = 16 clocks 5h = 32 clocks (default value after RESETt) 6h = 64 clocks 7h = no delay

3.3.6 Configuration Control Register 5 (CCR5)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Reserved	Reserved	ARREN	LBR1	Reserved	Reserved	Reserved	WT_ALLOC

Table 3.7 CCR5 Bit Definitions

Bit Name	Bit No.	Description
ARREN	5	If set, enables all Address Region Registers (ARRs). If clear, disables the ARR registers. If SM3 is set, ARR3 is enabled regardless of the ARREN setting.
LBR1	4	If set, LBA# pin is asserted for all accesses to the 640KBytes - 1MByte address region. See section 4.3 for more information on enabling/disabling LBA# for specific address regions.
WT_ALLOC	0	If set, new cache lines are allocated for both read misses and write misses. If clear, new cache lines are only allocated on read misses.

3.4 Address Region Registers (ARR0-7)

The Address Region Registers (ARRs) are used to define up to eight memory address regions. Each ARR has three 8-bit registers associated with it which define the region starting address and block size. Table 3-6 below shows the general format for each ARR and lists the index assignments for the ARR's starting address and block size.

The region starting address is defined by the upper 12 bits of the physical address. The region size is defined by the BSIZE(3-0) bits as shown in Table 3-7. The BIOS and/or its utilities should allow definition of all ARRs. There is one restriction when defining the address regions using the ARRs. The region starting address must be on a block size boundary. For example, a 128KByte block is allowed to have a starting address of 0KBytes, 128KBytes, 256KBytes, and so on.

Table 3.8 ARRx Index Assignments

Address Region Register	Starting Address			Region Block Size	
	A31-A24	A23-A16	A15-A12	BSIZE(3-0)	
	Bits (7-0)	Bits (7-0)	Bits (7-4)	Bits (3-0)	
ARR0	C4h	C5h	C6h		
ARR1	C7h	C8h	C9h		
ARR2	CAh	CBh	CCh		
ARR3	CDh	CEh	CFh		
ARR4	D0h	D1h	D2h		
ARR5	D3h	D4h	D5h		
ARR6	D6h	D7h	D8h		
ARR7	D9h	DAh	DBh		

Table 3.9 BSIZE(3-0) Bit Definition

BSIZE(3-0)	ARR(0-6) Region Size	ARR7 Region Size
0h	Disabled	Disabled
1h	4 KBytes	256 KBytes
2h	8 KBytes	512 KBytes
3h	16 KBytes	1 MByte
4h	32 KBytes	2 MBytes
5h	64 KBytes	4 MBytes
6h	128 KBytes	8 MBytes
7h	256 KBytes	16 MBytes
8h	512 KBytes	32 MBytes
9h	1 MByte	64 MBytes
Ah	2 MBytes	128 MBytes
Bh	4 MBytes	256 MBytes
Ch	8 MBytes	512 MBytes
Dh	16 MBytes	1 Gbytes
Eh	32 MBytes	2 Gbytes
Fh	4 GBytes	4 GBytes

3.5 Region Control Registers (RCR0-7)

The RCRs are used to define attributes, or characteristics, for each of the regions defined by the ARRs. Each ARR has a corresponding RCR with the general format shown below.

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Reserved	Reserved	NLB	WT	WG	WL	WWO	RCD/RCE

Note: RCD is defined for RCR0-RCR6. RCE is defined for RCR7 only.

Table 3.10 RCR Bit Definitions

Bit Name	Bit No.	Description
RCD	0	Applicable to RCR(0-6) only. If set, the address region specified by the corresponding ARR is non-cacheable.
RCE	0	Applicable to RCR7 only. If set, the address region specified by ARR7 is cacheable and implies that address space outside of the region specified by ARR7 is non-cacheable.
WW0	1	If set, weak write ordering is enabled for the corresponding region.
WL	2	If set, weak locking is enabled for the corresponding region.
WG	3	If set, write gathering is enabled for the corresponding region.
WT	4	If set, write through caching is enabled for the corresponding region.
NLB	5	If set, LBA# is negated for the corresponding region.

3.5.1 Detailed Description of RCR Attributes

Region Cache Disable (RCD)

Setting RCD=1 defines the corresponding address region as non-cacheable. RCD prevents caching of any access within the specified region. Additionally, RCD implies that high performance features are disabled for accesses within the specified address region. Bus cycles issued to memory addresses within the specified region are single cycles with the CACHE# pin negated. If KEN# is asserted for a memory access within a region defined non-cacheable by RCD, the access is not cached.

Region Cache Enable (RCE)

Setting RCE=1 defines the corresponding address region as cacheable. RCE is applicable to ARR7 only. RCE in combination with ARR7, is intended to define the Main Memory Region. All memory outside ARR7 is non-cacheable when RCE is set. This is intended to define all unused memory space as non-cacheable. If KEN# is negated for an access within a region defined cacheable by RCE, the access is not cacheable.

Weak Write Ordering (WWO)

Setting WWO=1 enables weak write ordering for the corresponding address region. Weak Write Ordering allows the ST6x86 to retire writes out of sequence to the internal cache only. External write cycles always occur in sequence (strongly ordered). WWO is only applicable to memory regions that have been cached and designated as write-back. WWO should never be enabled for memory mapped I/O.

Weak Locking (WL)

Setting WL=1 enables weak locking for the corresponding address region. With WL enabled, all bus cycles are issued with the LOCK# pin negated except for page table accesses and interrupt acknowledge cycles. WL negates bus locking so that previously non-cacheable cycles can be cached. Typically, XCHG instructions, instructions preceded by the LOCK prefix, and descriptor table accesses are locked cycles. Setting WL allows the data for these cycles to be cached.

Weak Locking (WL) implements the same function as NO_LOCK except that NO_LOCK is a global enable. The NO_LOCK bit of CCR1 enables weak locking for the entire address space, whereas the WL bit enables weak locking only for specific address regions.

Write Gathering (WG)

Setting WG=1 enables write gathering for the corresponding address region. With WG enabled, multiple byte, word or dword writes to sequential addresses that would normally occur as individual write cycles are combined and issued as a single write cycle. WG improves bus utilization and should be used for memory regions that are not sensitive to the "gathering". WG can be enabled for both cacheable and non-cacheable regions.

Write Through (WT)

Setting WT=1 defines the corresponding address region as write-through instead of write-back. Any system ROM that is allowed to be cached by the processor should be defined as write-through.

LBA# Not Asserted (NLB)

Setting NLB=1 prevents the ST6x86 from asserting the Local Bus Access (LBA#) output pin for accesses to that address region. The RCR regions in combination with the LBA# pin can be used to define local bus address regions. The LBA# signal can then used by external hardware as an indication that accesses are occurring to the local bus.

3.5.2 Attributes for Accesses Outside Defined Regions

If an address is accessed and it is not in the region defined by the ARRs and ARR7 is defined with RCE=1, the following conditions apply:

- •The memory access is not cached regardless of the state of KEN#.
- •The LBA# pin is asserted.
- •Writes are not gathered.
- •Strong locking occurs.
- •Strong write ordering occurs.

3.5.3 Attributes for Accesses in Overlapped Regions

If two defined address regions overlap (including NC1 and LBR1) and conflicting attributes are specified, the following attributes take precedence:

- •The LBA# pin is asserted.
- •Write-back is disabled.
- •Writes are not gathered.
- Strong locking occurs.
- •Strong write ordering occurs.
- •The overlapping regions are non-cacheable.

Example 1: Overlapping Regions with Conflicting Cacheability

Since the CCR0 bit NC1 affects cacheability, a potential exists for conflict with the ARR7 main memory region which also affects cacheability. This overlap in address regions with conflicting cacheability is a typical configuration for a PC environment. In this case, NC1 takes precedence over the ARR7/RCE setting because non-cacheability always takes precedence. For example, for the following settings:

- NC1-1
- ARR7 = 0-16 Mbytes
- RCR7 bit RCE = 1,

The ST6x86 cache accesses are shown in Table 3-11.

Table 3.11 Cacheability for Example 1

Address Region	Cacheable	Comments
0 to 640 KBytes	Yes	ARR7/RCE setting.
640 KBytes- 1 MByte	No	NC1 takes precedence over ARR7/RCE setting.
1 MByte - 16 MBytes	Yes	ARR7/RCE setting.
16 MBytes - 4 GBytes	No	Default setting.

Example 2: Overlapping Regions with Conflicting Local Bus Designations

Since the CCR5 bit LBR1 affects LBA# assertion, a potential exists for conflict with the RCR NLB bit, which also affects LBA# assertion. Preferably, regions/bits are defined such that there are no conflicting regions. However, in cases where there is a region overlap the LBR1 bit takes precedence over NLB. For example, for the following settings:

- LBR1=1
- ARR0 = 0-16 Mbytes
- RCR0 NLB=1,

The ST6x86 LBA# pin's behaviour is shown in Table 3-12.

Table 3.12 LBA# Behaviour for Example 2

Address Region	LBA# Behaviour	Comments
0 to 640 KBytes	Negated	ARR0/NLB0 setting.
640 KBytes- 1 MByte	Asserted	LBR1 takes precedence over ARR0/NLB0 setting.
1 MByte - 16 MBytes	Negated	ARR0/NLB0 setting.
16 MBytes - 4 GBytes	Asserted	Default setting.

3.5.4 Attributes for Accesses with Conflicting Signal Pin Inputs

The characteristics of the regions defined by the ARRs and the RCRs may also conflict with indications by hardware signals (i.e., KEN#, WB/WT#). The following paragraphs describe how conflicts between register settings and hardware indicators are resolved.

Non-cacheable Regions and KEN#

Regions which have been defined as non-cacheable (RCD=1) by the ARRs and RCRs may conflict with the assertion of the KEN# input. If KEN# is asserted for an access to a region defined as non-cacheable, the access is not cached. Regions defined as non-cacheable by the ARRs and RCRs take precedence over KEN#. The NC1 bit also takes precedence over the KEN# pin. If NC1 is set, any access to the 640k-1 Mbyte address region with KEN# asserted is not cached.

Write-through Regions and WB/WT#

Regions which have been defined as write-through (WT=1) may conflict with the state of the WB/WT# input to the ST6x86. Regions defined as write-through by the ARRs and RCRs remain write-through even if WB/WT# is asserted during accesses to these regions. The WT bit in the RCRs takes precedence over the state of the WB/WT# pin in cases of conflict.

4.0 Recommended ST6x86 Configuration Register Settings

4.1 PC Memory Model

Table 4.1 PC Memory Model

Address Space	Address Range	Cacheable	Weak Writes	Weak Locks	Write Gath- ered	Write- through	NOTES
DOS Area	0-9FFFFh	Yes	Yes	No	Yes	No	
Video Buffer	A0000-BFFFFh	No	No	No	Yes	No	Note 1
Video ROM	C0000-C7FFFh	Yes	No	No	No	Yes	Note 2
Expansion Card/ROM Area	C8000h-DFFFFh	No	No	No	No	No	
System ROM	E0000h-FFFFFh	Yes	No	No	No	Yes	Note 2
Extended Memory	100000h-Top of Main Memory	Yes	Yes	No	Yes	No	
Unused/PCI MMIO	Top of Main Mem- ory-FFFF FFFFh	No	No	No	No	No	Note 3

Table 4-1 defines the allowable attributes for a typical PC memory model. Actual recommended configuration register settings for an example PC system are listed in Appendix F.

Notes:

1. Video Buffer Area

A non-cacheable region must be used to enforce strong cycle ordering in this area and to prevent caching of video RAM. The video ram area is sensitive to bus cycle ordering. The VGA controller can perform logical operations which depend on strong cycle ordering (found in Windows 3.1 code). To guarantee that the ST6x86 performs strong cycle ordering, a non-cacheable area must be established to cover the video ram area.

Video performance is greatly enhanced by gathering writes to Video RAM. For example, video performance benchmarks have been found to use REP STOSW instructions that would normally execute as a series of sequential 16-bit write cycles. With WG enabled, groups of four 16-bit write cycles are reduced to a single 64-bit write cycle.

2. Video ROM and System ROM

Caching of the Video and System ROM areas is permitted, but is normally non-cacheable because NC1 is set. If these areas are cached, they must be cached as write-through regions. Benchmarking on ST6x86 systems in a Windows environment has shown no benefit to caching these ROM areas. Therefore, it is recommended that these areas be set as non-cacheable using the NC1 bit in CCR0.

3. Top of Main Memory-FFFFFFFh (Unused/PCI Memory Space)

Unused/PCI Memory Space immediately above physical main memory must be defined as non-cacheable to ensure proper operation of memory sizing software routines and to guarantee strong cycle ordering. Memory discovery routines must occur with cache disabled to prevent read sourcing from the write buffers. Also, PCI memory mapped I/O cards that may exist in this address region may contain control registers or FIFOs that depend on strong cycle ordering.

The appropriate non-cacheable region must be established using ARR7. For example, if 32 Mbytes (0000000-1FFFFFFh) are installed in the system, a non-cacheable region must begin at the 32 Mbyte boundary (2000000h) and extend through the top of the address space (FFFFFFFFh). This is accomplished by using ARR7 (Base = 0000 0000h, BSize=32Mbytes) in combination with RCE=1.

4.2 General Recommendations

4.2.1 Main Memory

Memory discovery routines should always be executed with the L1 cache disabled. By default, L1 caching is globally disabled following reset because the CD bit in Control Register 0 (CR0) is set. Always ensure the L1 cache is disabled by setting the CD bit in CR0 or by programming an ARR to "4 Gbyte cache disabled" before executing the memory discovery routine. Once BIOS completes memory discovery, ARR7 should be programmed with a base address of 0000000h and with a "Size" equal to the amount of main memory that was detected.

The intent of ARR7 is to define a cacheable region for main memory and simultaneously define unused/PCI space as non-cacheable. More restrictive regions are intended to overlay the 640k to 1Mbyte area. Failure to program ARR7 with the correct amount of main memory can result in the following:

- Incorrect memory sizing by the operating system eventually resulting in failure,
- PCI devices not working correctly or causing system hangs,
- Low performance if ARR7 is programmed with a smaller size than the actual amount of memory.

If the granularity selection in ARR7 does not accommodate the exact size of main memory, unused ARRs can be used to fill-in as non-cacheable regions. All unused/PCI memory space must always be set as non-cacheable.

4.2.2 I/O Recovery Time (IORT)

Back-to-back I/O writes followed by I/O reads may occur too quickly for a peripheral to respond correctly. Historically, programmers have inserted several "JMP \$+2" instructions in the hope that code fetches on the bus would create sufficient recovery time. The ST6x86's Branch Target Buffer (BTB) typically eliminates these external code fetches, thus the previous method of guaranteeing I/O recovery no longer applies. For the ST6x86, one approach to dealing with this issue is to insert I/O write cycles to a dummy port. I/O write cycles in the form "out imm,reg" are easily implemented as shown below:

OLD IORT	NEW IORT
out 21h,al	out 21h,al
jmp \$+2	out 80h,al
jmp \$+2	out 80h,al
jmp \$+2	out 80h,al
in al,21h	in al,21h

The ST6x86 incorporates an alternative method for implementing I/O recovery time using user selectable delay settings. See the section on ST6x86 IORT settings below.

4.2.3 BIOS Creation Utilities

BIOS creation utilities or setup screens must have the capability to easily define and modify the contents of the ST6x86 configuration registers. This allows OEMs and integrators to easily configure these register settings with the values appropriate for their system design.

4.2.4 Branch Target Buffer (BTB)

In the default state, the ST6x86 BTB stores target addresses for near change-of-flow instructions (COFs) only. To enhance the performance of the ST6x86, the BTB should be configured to store target addresses for both near and far COFs. This feature is controlled through reserved configuration and test registers. Sample code used to enable this feature is listed in Appendix G.

4.3 Recommended Bit Settings

4.3.1 NC1

The NC1 bit in CCR0 is a predefined non-cacheable region from 640k to 1MByte. The 640k to 1MByte region should be non-cacheable to prevent L1 caching of expansion cards using memory mapped i/o (MMIO). Setting NC1 also implies that the video BIOS and system BIOS are non-cacheable. Experiments with both the ST6x86 and Pentium show that modern operating systems and benchmark applications (such as WinStone95) are unchanged when caching/non-caching system and video BIOS.

Suggested setting

NC1= 1

4.3.2 NO LOCK

NO_LOCK enables weak locking for the entire address space. NO_LOCK may cause failures for software that requires locked cycles in order to operate correctly.

Suggested setting

 $NO_LOCK = 0$

4.3.3 LOCK NW

Once set, LOCK_NW prohibits software from changing the NW bit in CR0. Since the definition of the NW bit is the same for both the ST6x86 and the Pentium, it is not necessary to set this bit.

Suggested setting

 $LOCK_NW = 0$

4.3.4 WPR1

WPR1 forces cacheable accesses in the 640k to 1MByte address region to be write-protected. If NC1 is set (recommended setting), all caching is disabled from 640k to 1MByte and WPR1 is not required. However, if ROM areas within the 640k-1MByte address region are cached, WPR1 should be set to protect against errant self-modifying code.

Suggested setting

WPR1 = 0 unless ROM areas are cached

4.3.5 LINBRST

Linear Burst (LINBRST) allows for an alternate address sequence for burst cycles. The system logic and motherboard design must also support this feature in order for the ST6x86 to function properly with this bit enabled. Linear Burst provides higher performance than the default "1+4" burst sequence, but should only be enabled if the system is designed to support it.

If the system does support linear burst, BIOS should enable this feature in both the system logic and the ST6x86 prior to enabling the L1 cache.

Suggested setting

LINBRST = 0 unless linear burst supported by the system

4.3.6 MAPEN

When set to 1h, the MAPEN bits allow access to all ST6x86 configuration registers including indexes outside the C0h-CFh and FCh-FFh ranges. MAPEN should be set to 1h only to access specific configuration registers and then should be cleared after the access is complete.

Suggested setting

MAPEN(3-0)= 0 except for specific configuration register accesses

4.3.7 IORT

I/O recovery time specifies the minimum number of bus clocks between I/O accesses for the CPU's bus controller. The system logic typically also has a built-in method to select the amount of I/O recovery time. It is preferred to configure the system logic with the I/O recovery time setting and set the CPU for a minimum I/O recovery time delay.

Suggested setting

IORT(2-0) = 7

4.3.8 DTE EN

DTE_EN allows Directory Table Entries (DTE) to be cached on the ST6x86. This provides a performance improvement for some applications that access and modify the page tables frequently.

Suggested setting

 $DTE_EN = 1$

4.3.9 CPUIDEN

When set, the CPUIDEN bit enables the CPUID instruction and CPUID detection. By default, the CPUID instruction is disabled (CPUIDEN=0). In the default state, the CPUID opcode 0FA2 causes an invalid opcode exception. Additionally, the CPUID bit in the EFLAGS register cannot be modified by software. When enabled the CPUID opcode is enabled and the CPUID bit in the EFLAGS can be modified. The CPUID instruction can then be called to inspect the type of CPU present.

CPUID is disabled by default to guarantee compatibility with popular software that improperly uses CPUID and misidentifies the ST6x86. Misidentification of the processor can eventually result in runtime failures.

Suggested setting

CPUIDEN = 0

4.3.10 WT ALLOC

Write Allocate (WT_ALLOC) allows L1 cache write misses to cause a cache line allocation. This feature improves the L1 cache hit rate resulting in higher performance especially for Windows applications.

Suggested setting

WT_ALLOC= 1

4.3.11 LBR1

LBR1when set causes the LBA# (Local Bus Access) pin to be asserted for accesses between 640k to 1MByte. This feature is not used for most systems.

Suggested setting

LBR1= 0

APPLICATION NOTE

4.3.12 ARREN

The ARREN bit enables/disables all eight ARRs. When ARREN is cleared (default), the ARRs can be safely programmed. Most systems will need to use at least one address region register (ARR). Therefore, ARREN should always be set after the ARRs and RCRs have been initialized.

Suggested setting

ARREN = 1 after initializing ARR0-ARR7, RCR0-RCR7

4.3.13 ARR7 and RCR7

Address Region 7 (ARR7) defines the Main Memory Region (MMR). This region specifies the amount of cacheable main memory and it's attributes. Once BIOS completes memory discovery, ARR7 should be programmed with a base address of 0000000h and with a "Size" equal to the amount of main memory installed in the system. Memory accesses outside this region are defined as non-cacheable to ensure compatibility with PCI devices.

Suggested settings

ARR7 Base Addr= 0000 0000h

ARR7 Block Size= amount of main memory

RCR7 RCE= 1

RCR7 WWO= 1

RCR7 WL= 0

RCR7 WG= 1

RCR7 WT= 0

RCR7 NLB= 0

If the granularity selection in ARR7 does not accommodate the exact size of main memory, unused ARRs can be used to fill-in as non-cacheable regions (RCD = 1) as shown in Table 4-2. All unused/PCI memory space must always be set as non-cacheable

Table 4.2 ARR Settings for Various Main Memory Sizes

Mem	ARR7		ARR6		ARR5		ARR4	
SIZE (MB)	Base (hex)	Size (MB)	Base (hex)	Size (MB)	Base (hex)	Size (MB)	Base (hex)	Size (MB)
8	0	8						
16	0	16						
24	0	32	0180 0000	8				
32	0	32						
40	0	64	0300 0000	16	0280 0000	8		
48	0	64	0300 0000	16				
64	0	64						
72	0	128	0600 0000	32	0500 0000	16	0480 0000	8
80	0	128	0600 0000	32	0500 0000	16		
96	0	128	0600 0000	32				
128	0	128						
160	0	256	0E00 0000	32	0C00 0000	32	0A00 0000	32
192	0	256	0E00 0000	32	0C00 0000	32		
256	0	256						

4.3.14 SMM Features

The ST6x86 supports SMM mode through the use of the SMI# and SMIACT# pins, and a dedicated memory region for the SMM address space. SMM features must be enabled prior to servicing any SMI interrupts. The following paragraphs describe each of the SMM features and recommended settings.

USE_SMI

Prior to servicing SMI interrupts, SMM-capable systems must enable the SMM pins by setting USE_SMI=1. The SMM hardware pins (SMI# and SMIACT#) are disabled by default.

SMAC

If set, any access to addresses within the SMM address space accesses SMM memory instead of main memory. Setting SMAC allows access to the SMM memory without servicing an SMI. Additionally, SMAC allows use of the SMINT instruction (software SMI). This bit may be enabled to initialize or test SMM memory but should be cleared for normal operation.

SM3 and ARR3

Address Region Register 3 (ARR3) can be used to define the System Management Address Region (SMAR). Systems that use SMM features must use ARR3 to establish a base and limit for the SMM address space.

Only ARR3 can be used to establish the SMM region.

Typically, SMAR overlaps normal address space. RCR3 defines the attributes for both the SMM address region AND the normal address space. If SMAR overlaps main memory, write gathering should be enabled for ARR3. If SMAR overlaps video memory, ARR3 should be set as non-cacheable and write gathering should be enabled.

NMI EN

The NMI_EN bit allows NMI interrupts to occur within an SMI service routine. If this feature is enabled, the SMI service routine must guarantee that the IDT is initialized properly to allow the NMI to be serviced. Most systems do not require this feature.

SMI LOCK

Once the SMM features are initialized in the configuration registers, they can be permanently locked using the SMI_LOCK bit. Locking the SMM related bits and registers prevents applications from tampering with these settings. Even if SMM is not implemented, setting SMI_LOCK in combination with SMAC=0 prevents software SMIs from occurring.

Once SMI_LOCK is set, it can only be cleared by a processor RESET. Consequently, setting SMI_LOCK makes system/BIOS/SMM debugging difficult. To alleviate this problem, SMI_LOCK must be implemented as a user selectable "Secure SMI (enable/disable)" feature in CMOS setup. If SMI_LOCK is not user selectable, it is recommended that SMI_LOCK = 0 to facilitate system debug.

Suggested settings for systems not using SMM

 $USE_SMI = 0$ SMAC = 0 SM3 = 0

ARR3 = may be used as normal address region register

 $SMI_LOCK = 0$ $NMI_EN = 0$

Suggested settings for systems using SMM

USE_SMI = 1 SMAC = 0 SM3 = 1 ARR3 Base Addr = as required ARR3 Block Size= as required SMI_LOCK = 0 NMI_EN = 0

4.3.15 Power Management Features

SUSP_HALT

Suspend on Halt (SUSP_HLT) permits the CPU to enter a low power suspend mode when a HLT instruction is executed. Although this provides some power management capability, it is not optimal.

Suggested setting

SUSP_HALT = 0

USE_SUSP

In addition to the HLT instruction, low power suspend mode may be activated using the SUSP# input pin. In response to the SUSP# input, the SUSPA# output indicates when the ST6x86 has entered low power suspend mode. Systems that support the ST6x86's low power suspend feature via the hardware pins must set USE_SUSP to enable these pins.

Suggested setting

USE_SUSP = 0 unless hardware suspend pins supported

5.0 Programming Model Differences

5.1 Instruction Set

The ST6x86 supports the 486 instruction set. Pentium extensions for virtual mode, additional debug capability, and internal counters are not supported.

5.2 Configuring Internal ST6x86 Features

The ST6x86 supports configuring internal features through I/O ports. The ST6x86 does not support configuring internal features through the WRMSR and RDMSR instructions which are treated as invalid opcodes.

5.3 INVD and WBINVD Instructions

The INVD and WBINVD instructions are used to invalidate the contents of the internal and external caches. The WBINVD instruction first writes back any modified lines in the cache and then invalidates the contents. It ensures that cache coherency with system memory is maintained regardless of the cache operating mode. Following invalidation of the internal cache, the CPU generates special bus cycles to indicate that external caches should also write back modified data and invalidate their contents.

On the ST6x86, the INVD functions identically to the WBINVD instruction. The ST6x86 always writes all modified internal cache data to external memory prior to invalidating the internal cache contents. In contrast, the Pentium invalidates the contents of its internal caches without writing back the "dirty" data to system memory. The Pentium behavior can potentially result in a data incoherency between the CPU's internal cache and system memory.

5.4 Control Register 0 (CR0) CD and NW Bits

The CPU's CR0 register contains, among other things, the CD and NW which are used to control the on-chip cache. CR0, like the other system level registers, is only accessible to programs running at the highest privilege level. Table 5.1 lists the cache operating modes for the possible states of the CD and NW bits.

The CD and NW bits are set to one (cache disabled) after reset. For highest performance the cache should be enabled in write-back mode by clearing the CD and NW bits to 0. Sample code for enabling the cache is listed in Appendix E. To completely disable the cache, it is recommended that CD and NW be set to 1 followed by execution of the WBINVD instruction. The ST6x86 cache always accepts invalidation cycles even when the cache is disabled. Setting CD=0 and NW=1 causes a General Protection fault on the Pentium, but is allowed on the ST6x86 to globally enable write-through caching.

Table 5.1 Cache Operating Mode

CD	NW	OPERATING MODES		
		Cache disabled.		
		Read hits access the cache.		
		Read misses do not cause line fills.		
		Write hits update the cache and system memory.		
1	1	Write hits change exclusive lines to modified.		
		Shared lines remain shared after write hit.		
		Write misses access memory.		
		Inquiry and invalidation cycles are allowed.		
		System memory coherency maintained.		
		Cache disabled.		
		Read hits access the cache.		
		Read misses do not cause line fills.		
1	0	Write hits update the cache.		
	O	Only write hits to shared lines and write misses update system memory.		
		Write misses access memory.		
		Inquiry and invalidation cycles are allowed.		
		System memory coherency maintained.		
		Cache enabled in Write-through mode.		
		Read hits access the cache.		
		Read misses may cause line fills.		
0	1	Write hits update the cache and system memory.		
		Write misses access memory.		
		Inquiry and invalidation cycles are allowed.		
		System memory coherency maintained.		
0	0	Cache enabled in Write-back mode.		
		Read hits access the cache.		
		Read misses may cause line fills.		
		Write hits update the cache.		
		Write misses access memory and may cause line fills if write allocation is enabled.		
		Inquiry and invalidation cycles are allowed.		
		System memory coherency maintained.		

6.0 Appendix

6.1 Appendix A - Sample Code: Detecting a SGS-THOMSON CPU

```
assume cs:_TEXT
public issgs
_TEXT segment byte public 'CODE'
                         *********
    Function:
               int issgs ()
    Purpose:
               Determine if SGS-THOMSON CPU is present.
               SGS-THOMSON CPUs do not change flags where flags
    Technique:
              change in an undefined manner on other CPUs
    Inputs:
               none
               ax = 1 SGS-THOMSON present, 0 if not
    Output:
_issgsproc
              near
                .386
               xor
                                  ; clear ax
                      ax, ax
               sahf
                                     ; clear flags, bit 1 always=1 in flags
                      ax, 5
               mov
                      bx, 2
               mov
                       bl
               div
                                  ; operation that doesn't change flags
               lahf
                                    ; get flags
                      ah, 2    ; check for change in flags
not_sgs    ; flags changed, therefore NOT SGS
               \mathtt{cmp}
                jne
                                     ; TRUE SGS CPU
                      ax, 1
               mov
                      done
                jmp
not_sgs:
                      ax, 0 ; FALSE NON-SGS CPU
               mov
done:
               ret
_issgs
         endp
TEXT ends
end
```

Figure 1

6.2 Appendix B - Sample Code: Determining CPU MHz

```
assume cs:_TEXT
public _cpu_speed
_TEXT segment para public 'CODE'
comment~
*************************
           unsigned long _cpu_speed( unsigned int )
Function:
           "C" style caller
           calculate elapsed time reg'd to complete a loop of IDIVs
Purpose:
Technique: Use the PC's high resolution timer/counter chip (8254)
           to measure elapsed time of a software loop consisting
           of the IDIV and LOOP instruction.
Definitions: The 8254 receives a 1.19318MHz clock (0.8380966 usec).
           One "tick" is equal to one rising clock edge applied
          to the 8254 clock input.
Inputs:
           ax = no. of loops for cpu_speed_loop
Returns:
           ax = no. of 1.19318MHz clk ticks reg'd to complete a loop
           dx = state of 8254 out pin
PortB
                         EQU
                                    061h
                         EQU
                                    043h
Timer_Ctrl_Reg
                                    042h
Timer_2_Data
                         EQU
stk$dx
                         EQU
                                    10
                                                            ;dx register offset
stk$ax
                                    14
                                                            ;dx register offset
                         EQU
stack$ax
                                    [bp]+stk$ax
                         EQU
stack$dx
                         EQU
                                    [bp]+stk$dx
Loop_Count
                         EQU
                                    [bp+16]+4
.386p
_cpu_speed
                  proc near
         pushf
                                                            ;save interrupt flag
         pusha
                                                       ; pushes 16 bytes on stack
         mov
                  bp,sp
                                                            ;init base ptr
                                                                      continued
```

Figure 2

```
;-----initialize the 8254 counter to "0", known value
               al,0b0h
      mov
       out
               Timer_Ctrl_Reg, al ;control word to set channel 2 count
       out
               80h,al
                                    ;I/O recovery time
               al,0ffh
      mov
       out
               Timer_2_Data, al
                                   ;init count to 0, 1sb
               80h,al ;I/O recovery time Timer_2_Data, al ;init count to 0, msb
               80h,al
       out
      out
;----get the number of loops from the caller's stack
               cx,Loop_Count ;loop count
      mov
;-----load dividend & divisor, clk count for IDIV depend on operands!
       xor
               edx,edx
                                    dividend EDX: EAX;
       xor
                eax,eax
                ebx,1
                                    ;divisor
       mov
;----enable the timer/counter's clock. Begin timed portion of test!
               ax, di
al, 1
       xchg
                                    ;save ax for moment
        or
               PortB, al
                                    ;enable timer/counter 2 clk
        out
               ax, di
                                    ;restore ax
       xchg
;-----this is the core loop.
       ALIGN 16
cpu_speed_loop:
       idiv
                ebx
        idiv
                ebx
        idiv
                ebx
        idiv
                ebx
        idiv
                ebx
        loop
                cpu_speed_loop
;-----disable the timer/counter's clk. End timed portion of test!
               ax, di
al, OFEH
       mov
        and
                PortB, al
        out
                                                              continued
```

Figure 2

```
;-----send latch status command to the timer/counter
       mov
                al, 0c8h
                                         ;latch status and count
       out
               Timer_Ctrl_Reg, al
                80h,al
                                         ;I/O recovery time
       out
;-----read status byte, and count value "ticks" from the timer/cntr
             al, Timer_2_Data
        in
                                         ;read status
        out
                80h,al
                                         ;I/O recovery time
       mov
                dl, al
                dx, 080h
        and
        shr
                dx, 7
                                         ;read LSB
        in
               al, Timer_2_Data
                                         ;I/O recovery time
        out
               80h,al
                bl, al
       mov
               al, Timer_2_Data
        in
                                         ;read MSB
        out
               80h,al
                                         ;I/O recovery time
       mov
                bh, al
       not
                \mathbf{b}\mathbf{x}
                                         ;invert count
;-----send command to clear the timer/counter
               al, Ob6h
       mov
               Timer_Ctrl_Reg, al
                                         ;clear channel 2 count
        out
                80h,al
                                         ;I/O recovery time
        out
                al, al
       xor
               Timer_2_Data, al
                                         ;set count to 0, 1sb
        out
                                         ;I/O recovery time
        out
                80h,al
        out
               Timer_2_Data, al
                                         ;set count to 0, msb
;-----put return values on the stack for the caller
       mov
               [bp+stk$ax], bx
       mov
               [bp+stk$dx], dx
        popa
                                          ;restores interrupt flag
        popf
        ret
_cpu_speed
               endp
.8086
_TEXT
      ENDS
END
```

Figure 2

6.3 Appendix C - Example CPU Type and Frequency Detection Program

```
* ****************************
 function: main()
                                WCP 8/22/95
 Purpose: a driver program to demonstrate:
         CPU detection
         CPU core frequency in Mhz.
 Returns: 0 if successful
 Required source code modules
  ST6x86_stat.c main() module (this file)
  id.asm
                 cpu identification code
  clock.asm
                 cpu timing loop
 Compile and Link instructions for Borland C++ or equivalent:
 bcc ST6x86 stat.c id.asm clock.asm
/* include directives */
 #include <stdio.h>
/* constants */
 #define TTPS 1193182 //high speed Timer Ticks per second in Mhz #define MHZ 1000000 //number of clocks in 1 Mhz
  #define LOOP_COUNT 0x2000 //core loop iterations
  #define RUNS 10 //number of runs to average
  #define DIVS
                      5
                             //# of IDIV instructions in the core loop
  #define ST6x86_IDIV_CLKS 17 //known clock counts for ST6x86
  #define ST6x86 LOOP CLKS 1
                            //known clock counts for P54
  #define P54_IDIV_CLKS 46
  #define P54_LOOP_CLKS 7
/* prototypes */
unsigned int issgs (void);
main(){
/* declarations */
unsigned char uc_sgs_cpu = 0;
                                            //SGS cpu? 0=no, 1=yes
unsigned int
                                              //number of runs to avg
                 i_runs = 0;
                 ui_idiv, ui_loop = 0;
unsigned int
                                              //instruction clk counts
                                                          continued
```

Figure 3

```
unsigned long ul_tt_cnt, ul_tt_sum = 0;
                                               //timer tick counts, sum
 unsigned int ui_core_loop_cntr = LOOP_COUNT; //core loop iterations
                                                //measured timer ticks
  float
             f_mtt = 0;
  float
             f_total_core_clks = 0;
                                                //calculated core clocks
  float
              f_total_time = 0;
                                                //measured time
  float
              f_mhz = 0;
                                                //mhz
/* ****** determine if SGS CPU is present ******** */
  //dectect if SGS CPU is present
    uc_sgs_cpu = issgs();
                                               //1=sgs, 0=non-sgs
  //display a msg
  if(uc_sgs_cpu) printf("\nSGS-THOMSON CPU present! ");
    else printf("\nSGS-THOMSON CPU not present! ");
 /* ************* determine CPU Mhz ************* */
 //count # of hi speed "timer ticks" to complete several runs of core loop
  for (i_runs = 0 ; i_runs < RUNS ; i_runs++) {</pre>
   ul_tt_cnt = cpu_speed( ui_core_loop_cntr );
   ul tt sum += ul tt cnt;
                                               //sum them all together
}//end for
 //compute the avg number of high speed "timer ticks" for the several runs
    f_mtt = ul_tt_sum / RUNS;
                                               //compute the average
 //initialize variables with the "known" clock counts for a ST6x86 or P54
  if(uc_sgs_cpu)ui_loop=ST6x86_LOOP_CLKS; else ui_loop=P54_LOOP_CLKS;
  if(uc_sgs_cpu)ui_idiv=ST6x86_IDIV_CLKS; else ui_idiv=P54_IDIV_CLKS;
 //determine the total number of core clocks.(5 idivs are in the core loop)
  f_total_core_clks = (float)ui_core_loop_cntr * (ui_idiv * DIVS + ui_loop)
 //the time it took to complete the core loop can be determined by the
 //ratio of measured timer ticks(mtt) to timer ticks per second(TTPS).
   f_total_time = f_mtt / TTPS;
//frequency can be found by the ratio of core clks to the total time.
  f_mhz = f_total_core_clks / f_total_time;
  f_mhz = f_mhz / MHZ;
                                               //convert to Mhz
 //display a msg
   printf("The core clock frequency is: %3.1f MHz\n\n",f_mhz);
   return(0);
}// end main
```

Figure 3

6.4 Appendix D- Sample Code: Programming ST6x86 Configuration Registers

6.4.1 Reading/Writing Configuration Registers

```
Sample code for setting NC1=1 in CCR0.
pushf
                              ; save the if flag
cli;
                             ;disable interrupts
     al, 0c0h
mov
                             ;set index for CCR0
     22h, al;
al, 23h
out
                             ;select CCR0 register
in
                             ;READ current CCR0 valueREAD
     ah, al
     ah, 2h;
                             ;MODIFY, set NC1 bitMODIFY
or
      al, 0c0h
                             ;set index for CCR0
mov
      22h, al
                             ;select CCR0 register
out
mov
      al, ah
      23h,al
                             ;WRITE new value to CCROWRITE
out
popf
                              ;restore if flag
```

Figure 4

6.4.2 Setting MAPEN

```
Sample code for setting MAPEN=1 in CCR3 to allow access to all of the
configuration registers.
pushf
                             ; save the if flag
                            ;disable interrupts
cli;
mov
      al, 0c3h
                             ;set index for CCR3
      22h, al
                             ;select CCR3 register
out
in
      al, 23h
                             ;current CCR3 valueREAD
      ah, al
mov
     ah,0Fh
                            ;clear upper nibble of ah
and
     ah, 10h;
                            ;MODIFY, set MAPEN(3-0)MODIFY
or
mov
     al, 0c3h
                             ;set index for CCR3
     22h, al
                             ;select CCR3 register
out
    al, ah
mov
     23h,al
                             ;WRITE new value to CCR3WRITE
out
popf
                             ;restore if flag
```

Figure 5

6.5 Appendix E - Sample Code: Controlling the L1 Cache

6.5.1 Enabling the L1 Cache

Figure 6

6.5.2 Disabling the L1 Cache

```
mov eax, cr0
or eax, 060000000h ;set the CD=1, NW=1 bits to disable caching
mov cr0, eax ;control register 0 write
wbinvd
```

Figure 7

6.6 Appendix F - Example Configuration Register Settings

Below is an example of optimized ST6x86 settings for a 16 MByte system with PCI. Since SMI address space overlaps Video RAM at A0000h, WG is set to maintain the settings of the underlying region ARRO. If SMI address space overlapped system memory at 30000h, only WWO and WG would be set. If SMI address space overlapped FLASH ROM at E0000h, only RCD would be set. Power management features are disabled in this example system.

Table 6.6 Configuration Register Settings

Register	Bit(s)	Setting	Description
CCR0	NC1	1	Disables caching from 640k-1MByte.
	USE_SMI	1	Enables SMI# and SMIACT# pins.
CCR1	SMAC	0	Always clear SMAC for normal operation.
CCRI	NO_LOCK	0	Enforces strong locking for compatibility.
	SM3	1	Sets ARR3 as SMM address region.
	LOCK_NW	0	Locking NW bit not required.
CCP2	SUSP_HLT	0	Power management not required for this system.
CCR2	WPR1	0	ROM areas not cached, so WPR1 not required.
	USE_SUSP	0	Power management not required for this system.
	SMI_LOCK	0	Locks SMI feature as initialized.
CCR3	NMI_EN	0	Servicing NMIs during SMI not required.
CCR3	LINBRST	0	Linear burst not supported in this system.
	MAPEN(3-0)	0	Always clear MAPEN for normal operation.
	IORT(2-0)	7	Sets IORT to minimum setting.
CCR4	DTE_EN	1	Enables DTE cache.
	CPUIDEN	0	Disables CPUID instruction for compatibility.
	WT_ALLOC	1	Enables write allocation for performance.
CCR5	LBR1	0	LBA# pin not required.
	ARREN	1	Enables all ARRs.
ARR0	BASE ADDR	A0000h	Video buffer base address = A0000h.
ARRU	BLOCK SIZE	6h	Video buffer block size = 128KBytes.
	RCD	1	
	WWO	0	Caching disabled for compatibility. Caching also disabled
DODO	WL	0	via NC1.
RCR0	WG	1	
	WT	0	Write gathering enabled for performance.
	NLB	0	
ADD4	BASE ADDR	C0000h	Expansion Card/ ROM base address = C0000h.
ARR1	BLOCK SIZE	7h	Expansion Card/ROM block size = 256KBytes.

continued

Table 6.6 Configuration Register Settings

-	_	_		
RCR1	RCD	1		
	WWO	0	Caching disabled for compatibility. Caching also disabled via NC1.	
	WL	0		
	WG	0	Caci iii ig disabled for compatibility. Caci iii ig also disabled via 1401.	
	WT	0		
	NLB	0		
ARR3	BASE ADDR	A0000h	SMM address region base address	
AKKS	BLOCK SIZE	4h	SMM address space = 32 KBytes	
	RCD	1		
	WWO	0	Caching disabled due to overlap with video buffer.	
DODO	WL	0		
RCR3	WG	1	Military that a smaller day to a select Military M	
	WT	0	Write gathering enabled due to overlap with video buffer.	
	NLB	0		
4007	BASE ADDR	0h	Main memory base address = 0h.	
ARR7	BLOCK SIZE	7 h	Main memory size = 16 MBytes.	
	RCE	1		
	WWO	1		
0007	WL	0	Caching, weak write ordering, and write gathering enabled for main memory.	
RCR7	WG	1		
	WT	0		
	NLB	0		
ARR(2,4-6)	BASE ADDR	0	ADD/O 4 C) disable d (default etets)	
	BLOCK SIZE	0	ARR(2,4-6) disabled (default state).	
RCR(2,4-6)	RCD	0		
	WWO	0		
	WL	0	RCR(2,4-6) not required due to corresponding ARRs dis-	
	WG	0	abled (default state).	
	WT	0		
	NLB	0		
	1	l .	1	

6.7 Appendix G - Sample Code: Enabling FAR COFs in BTB

```
Below is sample code that enables FAR COFs in the BTB.
;-----First, set MAPEN to allow access to all ST6x86 configuration regs
mov al, 0C3h
                         ;READ
out 22h, al
in al, 23h
mov ah, al
                        ; MODIFY
or ah, 10h
and ah, 1Fh
mov al, 0C3h
                        ;WRITE
out 22h, al
mov al, ah
out 23h, al
;-----Enable ST6x86 test register opcodes
mov al, 30h
                        ;READ debug register (index 30)
out 22h, al
in al, 23h
mov ah, al
                        ;MODIFY enable tr opcodes
or
    ah, (1 SHL 6)
mov al, 30h
                        ;WRITE debug reg (index 30h)
out 22h, al
mov al, ah
out 23h, al
;-----Enable FAR COF hits (index 5, bit 1)
mov ebx,28h
                        ;select index 5
movtr _tr1,_ebx
db 0Fh,26h,0CBh
                      ;opcodes for movtr _tr1,_ebx
movtr _eax,_tr2
                        ;READ test reg index 5
db 0Fh,24h,0D0h
                         ; opcodes for movtr _eax,_tr2
and eax, 0FFFFFFDh
                         ; MODIFY
                                                        continued
```

Figure 8

```
movtr _tr2,_eax
                           ;WRITE new data to test reg 5
     0Fh,26h,0D0h
                           ; opcodes for movtr _tr2,_eax
db
mov
      debug_reg_0,eax
                           ;save value for later
;-----Disable ST6x86 Test Register Opcodes
    al, 30h
22h, al
al, 23h
                           ;READ debug reg DBR0
mov
out
in
    ah, al
ah, OBFh
mov
                          ; MODIFY
                           ;turn off tr opcodes
and
      al, 30h
                           ;WRITE
mov
      22h, al
out
mov
     al, ah
     23h, al
out
;-----Restore mapen to default state
mov al, 0C3h out 22h, al
                             ;READ
      al, 23h
in
     ah, al
                           ; MODIFY
mov
and
    ah, 0Fh
                           ;turn off mapen
mov
      al, 0C3h
                          ;WRITE
      22h, al
out
      al, ah
23h, al
mov
out
```

Figure 8

6.8 Appendix H - Sample Code: Detecting L2 Cache Burst Mode

```
Purpose:
             This example program detects if the Linear Burst mode is supported.
 Method:
             There are 3 components (CPU, chipset, SPBSRAM) that must agree on the
            burst order. The CPU and chipset burst order can be determined by inspecting each
            devices' internal configuration registers. The SPBSRAM devices must be interrogated
             by a software algorithm (below) to determine if "linear burst mode" is enabled/
             supported correctly.
 Algorithm:
             If the CPU and chipset are programmed for linear burst mode and a known data
             pattern exists in memory, then the burst mode of the SPBSRAMs can be
             determined by performing a cache line burst and then inspecting the data pattern.
             In this example, the SIS5511 chipset is used with a SGS-THOMSON ST6x86
 Application:
              CPU.
 Environment: This program is a REAL mode DOS program to serve as an example. This
              example algorithm should be ported to BIOS.
 Warnings:
              For simplicity, this program does not check to see which CPU or chipset is
              present nor does it check to see if the CPU is in the REAL mode before
              executing protected instructions. Also, this program blindly overwrites data in the
              8000h segment of memory.
;version m510
                                          ;remove comment for TASM
DOSSEG
.MODEL
         SMALL
.DATA
Msg_1db
                0dh,0ah
db
          'ISLINBUR.EXE checks if L2 SRAMs are in Linear Burst Mode or'
db
           0dh,0ah
db
          'Toggle Burst mode for the SIS5511 chipset and the ST6x86 CPU.'
db
           0dh,0ah
           ıġı
db
Msq 2
                  0dh,0ah
        db
db
          'Test complete!'
db
           0dh,0ah
           ıġı
db
Msg_yes
                   db 0dh,0ah
db
          'The L2 SRAMs correctly operate in linear burst mode.'
db
           0dh,0ah
           1$1
db
Msg_no
                  db 0dh,0ah
db
          'ERROR: The L2 SRAMs incorrectly operate in linear burst mode.'
           0dh,0ah
db
db
           151
                                                                            continued
```

Figure 9

```
index_port
                dw
                        0CF8h
data_port
                dw
                        0CFCh
                        8000000h
pci_index
                dd
.STACK 100h
.CODE
.STARTUP
.486P
pushf
cli
;-----display a msg using a DOS call
       ax, seg Msg 1
mov
mov
       ds,ax
        dx,offset Msg_1
                                 ;set msg_1 start
mov
       ah,9h
                                 ;print string function
mov
        21h
int
                                 ;DOS int
;-----disable the L1 internal cache
call cache off
out
       80h,al
                                 ;write to PC diagnostic port
;----setup a work space in main memory to perform burst mode tests
;and initialize the memory work space with a known pattern
push
       ds
mov
        ax,8000h
                                 ; choose segment 8000h
mov
        ds,ax
mov
        al,0001h
mov
       byte ptr ds:[0],al
                                ; init memory locations
inc
        al
mov
       byte ptr ds:[8h],al
inc
       al
mov
       byte ptr ds:[10h],al
inc
       al
mov
       byte ptr ds:[18h],al
pop
;----enable the SiS5511 chipset's linear burst mode
mov
       al,51h
                                ;al=reg to read
       r_pci_reg
                                 ;READ al=reg contents
call
        ah,al
mov
                                 ;MODIFY set linbrst bit
or
        ah,8
        al,51h
mov
call
       w_pci_reg
                                 ;WRITE
;-----enable the CPU's linear burst mode
call
       en linbrst
;-----enable L1 caching
                                                             continued
       cache on
call
```

Figure 9

```
;-----burst several cache lines so that address 80000h is in the L2
       ; cache, but NOT in the L1 cache.
       ds
push
       ax,8000h
mov
                                          ; choose segment 8000h
mov
       ds,ax
       al,byte ptr ds:[0h]
                                         ;do a line fill to L2 and L1
mov
                                          ;fill L1 line 1
       al,byte ptr ds:[1000h]
mov
       al,byte ptr ds:[2000h]
                                         ;fill L1 line 1
mov
     al, byte ptr ds:[3000h]
                                         ;fill L1 line 1
mov
mov
       al, byte ptr ds:[4000h]
                                         fill L1 line 1,
;now 80000h exists only in the
;L2 cache (not in L1 anymore!)
;---burst a cache line so that address 80000h will hit the L2 cache SRAMs
      al, byte ptr ds:[8h]
mov
      ;***** Burst Pattern Table *****
      ; if SRAMs in linear burst mode, then
 ;L1 will be filled with:
  ; byte data
  ; 0
          01h
   ; 8
          02h
  ; 10
          0.3h
   ; 18
          04h
; if SRAMs in toggle burst mode, then
 ;L1 will be filled with:
  ; byte data
  ; 0
          0.3h
  ; 8
          02h
  ; 10
          01h
   ; 18
          04h
;-----Compare the cache line to the Burst Pattern Table above. The
; signature of the pattern will determine if the burst was
; linear or toggle.
       al, byte ptr ds:[10h]
                                          ; check byte ds:[10] in the L1
mov
       al,3h
                                          ;it will be a 1 if toggle mode
cmp
                                          ;it will be a 3 if linear mode
       ds
pop
      not_linear
jnz
is linear:
mov dx,offset Msg_yes
                                         ;SRAMs in linear burst mode
jmp
       over_not
not linear:
       dx,offset Msg_no
                                         ;SRAMs in toggle burst mode
mov
over_not:
wbinvd
;-----disable L1 internal cache
call
      cache_off
                                                             continued
```

Figure 9

```
;----restore chipset to toggle mode burst order
       al,51h
mov
                                       ;al=reg to read
                                       ;READ al=reg contents
call
       r_pci_reg
mov
       ah,al
and
       ah,0f7h
                                       ;MODIFY clr linbrst bit
       al,51h
mov
call
       w_pci_reg
                                       ;WRITE
       dis_linbrst
call
;----restore L1 caching
      cache on
call
done:
popf
;-----display a msg using a DOS call
       ax,seg Msg_2
mov
mov
       ds,ax
mov
       ah,9h
                                       ;print string function
       21h
                                       ;DOS int
int
;----return to the operating system
.EXIT
comment~***********************************
function
              r pci reg
             read the pci register at the index in al
purpose
             al= the index of the pci register
inputs
returns
             al= the data read from the pci reg
r_pci_reg PROC
pushf
push
        eax
push
cli
        dx,index_port
mov
       eax,0FFh
and
or
        eax,pci_index
out
        dx,eax
and
       al,3
       dx,data_port
mov
add
       dl,al
       al,dx
in
       al,bl
                                       ;preserve rtn value
xchg
       eax,pci_index
                                                         continued
mov
```

Figure 9

```
mov
        dx,index_port
        dx,eax
out
        dx
pop
pop
        eax
popf
        al,bl
xchq
ret
r_pci_reg ENDP
comment~***********************************
function
              w_pci_reg
              al= the index of the pci register ah= the data to write
inputs
             modifies chipset registers directly
outputs
returns
************************
w_pci_reg proc
pushf
push
        eax
push
        \mathbf{b}\mathbf{x}
push
        dx
cli
        bx,ax
                            ;preserve input value(s)
mov
        dx,index_port
mov
        eax,0FFh
and
or
        eax,pci_index
out
        dx,eax
        al,3
and
        dx,data_port
mov
        dl,al
add
        al,bh
                            ;recall data to write
mov
        dx,al
out
mov
        eax,pci index
mov
        dx,index_port
        dx,eax
out
        dx
pop
pop
        bx
pop
        eax
popf
ret
w_pci_reg ENDP
                                                          continued
```

Figure 9

```
comment~***********************************
function
          en_linbrst
          enable the ST6x86 linbrst bit
purpose
          none
inputs
          modifies the ST6x86 CPU registers directly
outputs
returns
          none
***********************
en_linbrst PROC
mov
    ax,0C3C3h
                     set LINBRST;
     22h,al
out
in
    al,23h
xchg ah,al
or
    ah,4
     22h,al
out
xchg ah,al
     23h,al
out
ret
en_linbrst ENDP
function
          dis_linbrst
          disable the ST6x86 linbrst bit
purpose
          none
inputs
          modifies the ST6x86 CPU registers directly
outputs
returns
          none
************************
dis_linbrst PROC
mov
    ax,0C3C3h
out
     22h,al
in
    al,23h
xchg ah,al
    ah,0fbh
                     ;clear the linbrst bit
and
     22h,al
out
xchg ah,al
    23h,al
out
ret
dis linbrst ENDP
comment~***********************************
          cache_off
function
purpose
          disables the L1 cache
inputs
          none
****************************
cache_off PROC
                                            continued
```

Figure 9

```
pushf
push
      eax
cli
mov
      eax,cr0
or
      eax,60000000h
mov
      cr0,eax
wbinvd
jmp
      $+2
pop
      eax
popf
ret
cache_off ENDP
comment~***********************************
function
             cache on
             enables the L1 cache
purpose
             none
inputs
returns
             none
*************************
cache_on PROC
pushf
push
      eax
cli
mov
     eax,cr0
     eax,9FFFFFFFh
and
mov
      cr0,eax
pop
      eax
popf
ret
cache_on ENDP
END
```

Figure 9

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